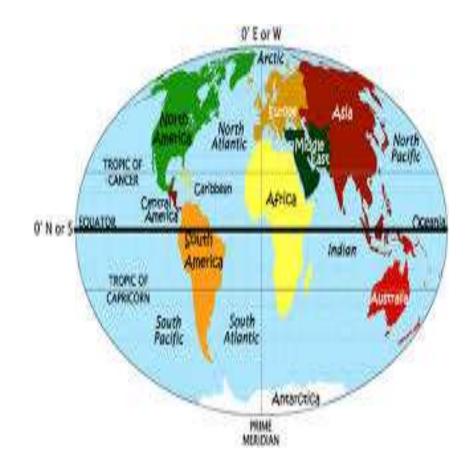
Precision Agriculture Past - - -- - - Present - - -- - - Future

Dr. Jim Schepers or Dr. Dennis Francis USDA-Agricultural Research Service (both happily retired)

Thanks -- for the invitation to the 2014 Precision Agriculture National Symposium

My first trip to Brazil (Sete Lagoas) was in January 1995

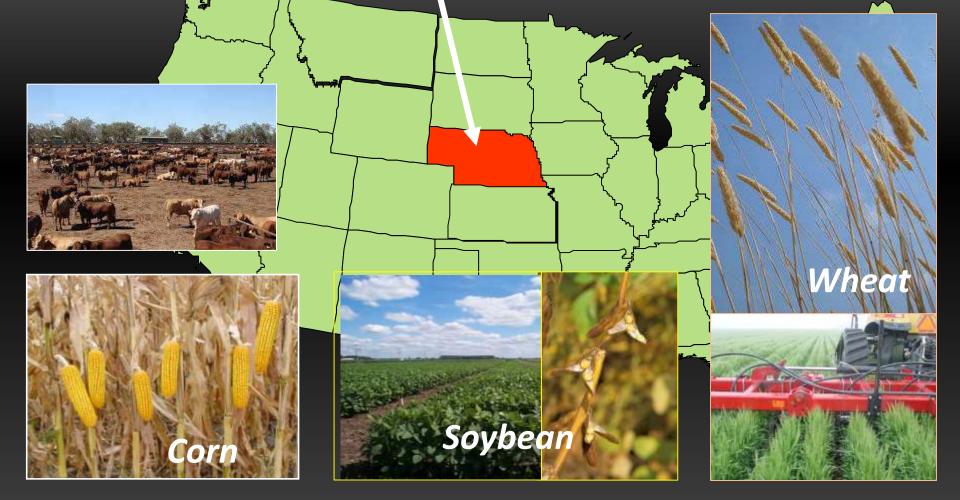








Nebraska



Farmers are great observers !



BUT

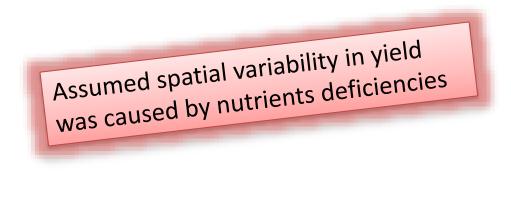
May not be able to explain their observations



AS SUCH

Producers welcome scientific information and are eager to learn from the discussion

Initial precision agricultural efforts were driven by industry



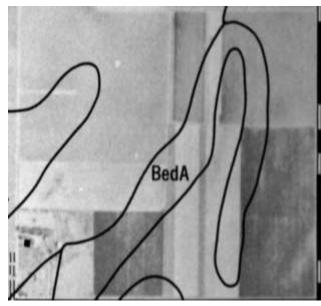


Six nutrients

Outcome: Spatial variability in crop vigor and yield was only partially removed

Need: Technologies to quantify yield variability

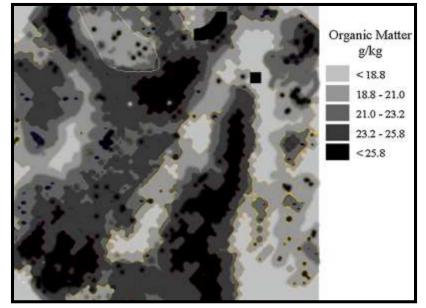
- Variable-rate multi-nutrient applications were based on soil testing data
- GPS was not available



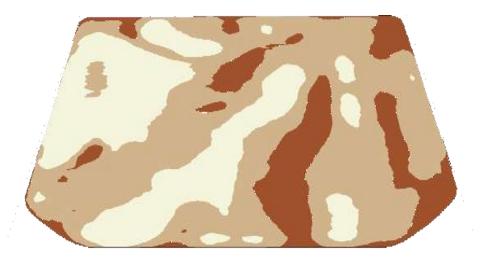
Soil Survey



Bare Soil Image



Grid Soil Sampling



Computer Generated Management Zones

Another Tool



Here In a sugar Language

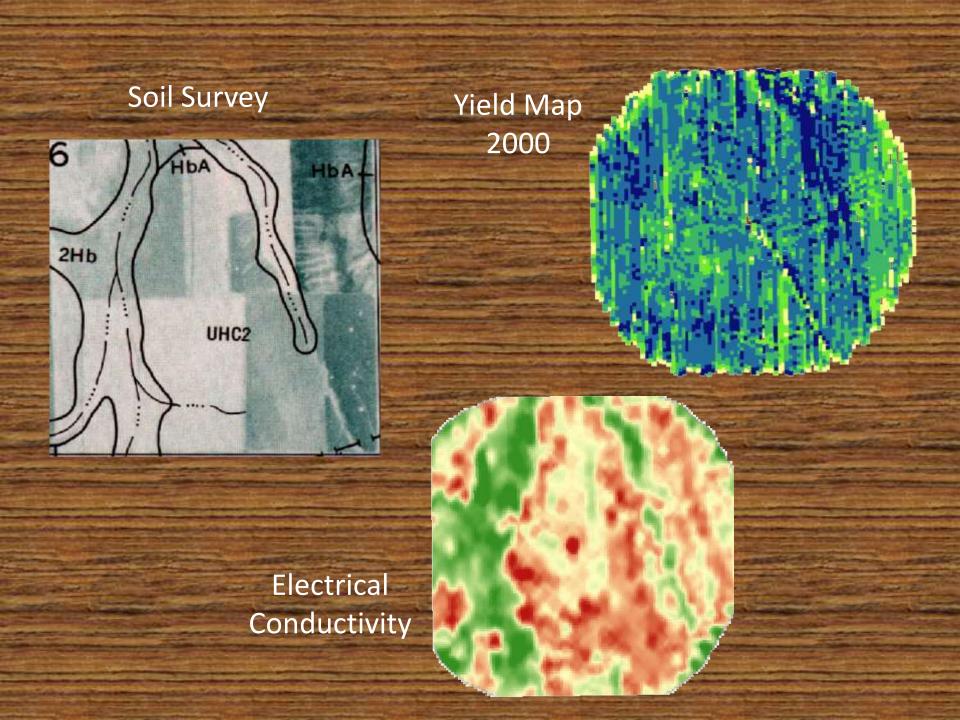
EM-38 (electro-magnetic induction)

The second se

Proxy for soil electrical conductivity

Electrical Conductivity Veris (electro-magnetic induction)





Computer Generated Management Zones

7

Incorporating...

Bare Soil Image

Elevation

Slope

EM-38

First yield-monitor combines were tested in 1992

Situation: Required three computers

- Grain flow
- Grain moisture
- GPS (initially scrambled)





- Yield-monitors are common on new combines
- Grain protein content monitors are now available
- Yield maps are not fully utilized

Crop canopy sensor research was initiated in 1993

Situation: Chlorophyll meters worked well for research purposes, but are not practical for commercial fields

Therefore: Need for mobile devices to provide information related to crop biomass (*size of the factory*) and canopy chlorophyll content (*photosynthesis*)



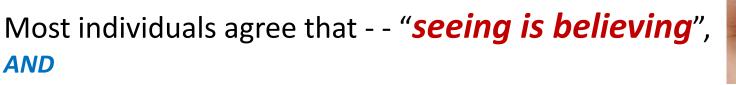
Introduced in 1990

First crop canopy sensors used natural lighting (*known as passive sensors*)

Problems:	clouds		
	shadows		
	changes in brightness during the day		

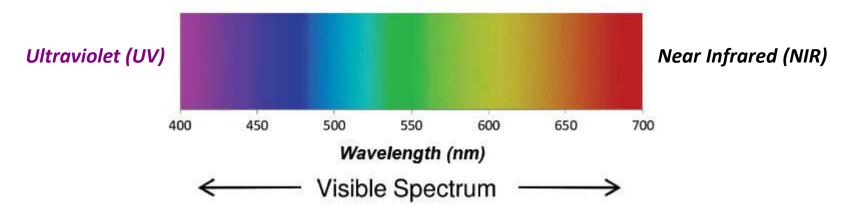
Active sensor research initiated in 1999

Attributes:	generated modulated light
	no affect of shadows
	operational any time of the day
	can be used to facilitate " on-the-go" nutrient applications





the human eye is especially sensitive to green colors



BUT

Humans cannot see near infrared light, which is reflected by living vegetation (*also called biomass*)

AS SUCH

Farmers largely base their assessment of crop vigor on "*greenness*" (*related to chlorophyll content and nitrogen status*)

Remember ----

Canopy sensors respond to "living biomass" and "chlorophyll content"

Treatments / N-rates

N Status

Canopy sensors can not quantify excess N AND Soil background reduces sensitivity

Similar

Sensors can be designed to be sensitive to *Greenness* - (i.e., chlorophyll and nitrogen status in most cases)

AND TO

near infrared (NIR) light - ("living vegetation" called biomass)

BASICALLY

NIR - size of the factory (cumulative indicator of canopy size) (number and size of leaves)

Chlorophyll - output potential of leaves via photosynthesis

RESULTING IN

Yield and potential profitability

- - - - This why we need to measure chlorophyll and biomass

Crop Circle ACS-430

or AgLeader OptRx

Functions Day or Night

Cotton Greece 2010

Mexico - White Corn, 2010



Irrigated Corn - Nebraska





Precision Agriculture (*Site-Specific Management*) is not a "*one-size-fits-all*" proposition or universal solution to address spatial variability

- Different field sizes
- Different crops
- Different soils
- Uncertainty about climate and water availability
- Spatial variability in nutrient status
- Availability of field equipment is important
- Implementation might require technical assistance

High yields may not be highly correlated with *profitability*

Sustainability requires a multi-year analysis

Perceptions - may not be true, but they are "REAL" in the minds of individuals



- I'm too old to learn
- Too expensive
- My fields are uniform
- I'm still farming, so my operation must be sustainable
- Too much risk
- I already demonstrate environmental stewardship
- Technical assistance is not available or is unreliable





RIGHT - Place Rate Time

What about the plant environment ?

How to create a better environment for plants ?

Form

Consider: compaction nutrient placement plant competition weeds

Approaches to Precision Agriculture

Proactive - Plan ahead and lock-in decisions

based on:

soil texture and water holding capacity nutrient information anticipated weather yield goal

Reactive - Monitor weather and crop vigor to make in-season adjustments (also called "adaptive management") according to: available soil water anticipated weather estimated nutrient losses thus far in the season crop vigor (sensors or remote sensing) changes in yield potential

Potentially Useful Technologies	United States	Brazil
Variable-rate planting	moderate	
Multiple-cultivar planting	low	
Variable-rate lime	high	
Variable-rate nutrients	moderate	
Yield mapping	high	How would you
Crop canopy sensors	moderate	populate the
Remote sensing	moderate	table ?
Climate & growth models	???	
High-clearance applicators	moderate	
Crop consultants	moderate ++	
Auto-guidance	high	

Harnessing Precision Agriculture information is like

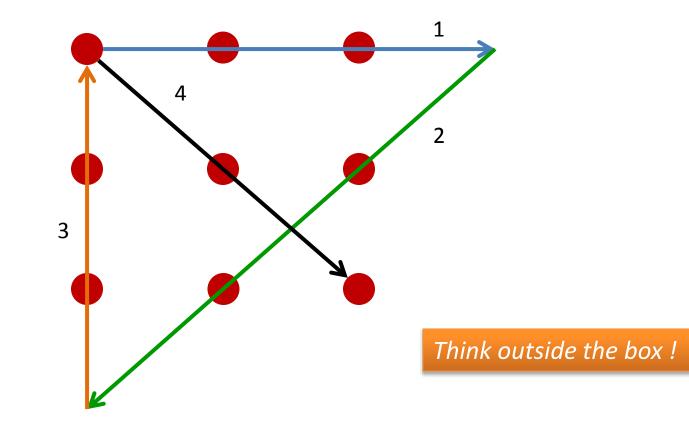


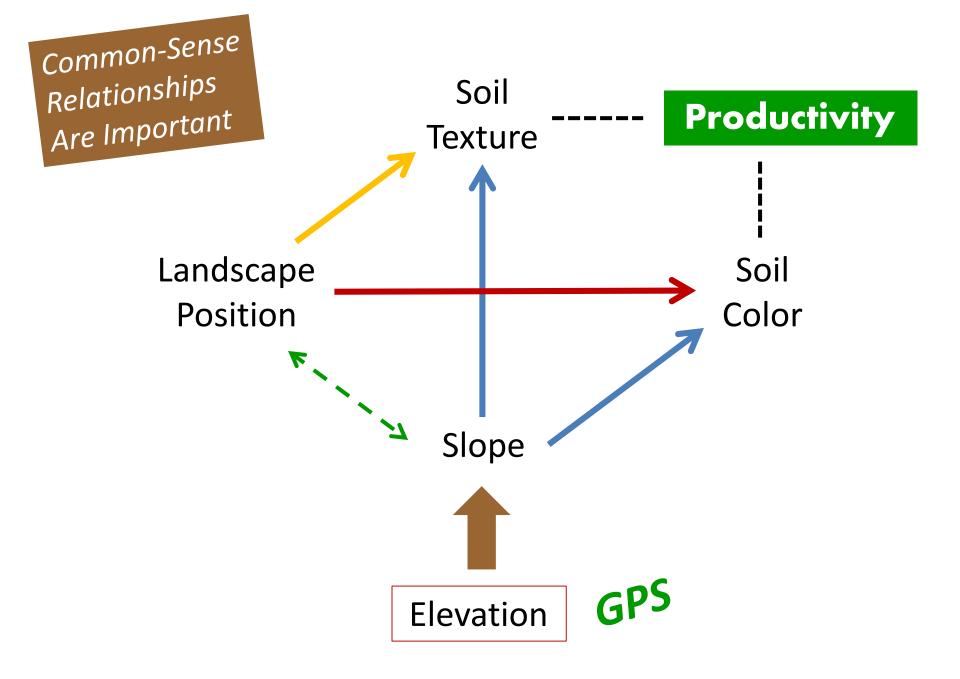
making sausage !

Needs multiple ingredients in the right proportions

Precision Agriculture is about *innovation* and *thinking outside the box*

How would you connect these nine points with *four continuous lines*?





So Much for the Concept of Precision Agriculture

How did the Embrapa / USDA-ARS partnership come to be ?

The relationship started in January 1995 - A friend, Walter Baethgen, from Uruguay put me in contact with Goncalo Franca with Embrapa at Sete Lagoas.



A graduate student, scientist with Li-Cor, and Jim Schepers tested prototype passive sensors with the assistance of Goncalo Franca and Evandro Mantovani (*also hosted by Bob Schaffert, Antonio Bahia, and Mauricio Lopes*).

Morethson Resende (water management) and Derli Santana (soil classification) traveled to Nebraska while on sabbatical leave (1995-1997).

A team of nine USDA-ARS scientists visited five Embrapa locations in 1996. Precision agriculture was identified as a discipline of interest for scientific exchanges. This was the beginning of the **LABEX** program.

LABEX Friends who spent time in Nebraska









Ariovaldo Luchiari

Moresthon Resende Ricardo Inamasu Evandro Mantovani

Others without Pictures

Scientists

Goncalo Franca Derli Santana Frederico Duraes

Jose Molin

Graduate Students

Antonio Coehlo Jaoa Camargo Neto Luciano Shiratsuchi

Lucas Amaral

Field Researchers - 2000











Ricardo Inamasu

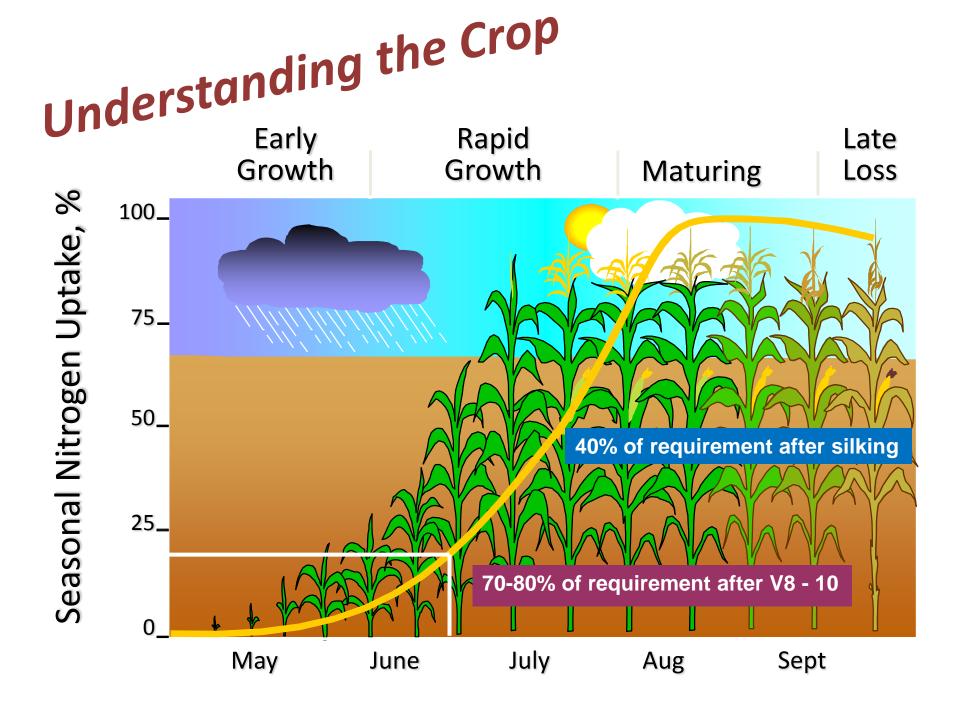
Examples of imagination, innovation, determination and execution

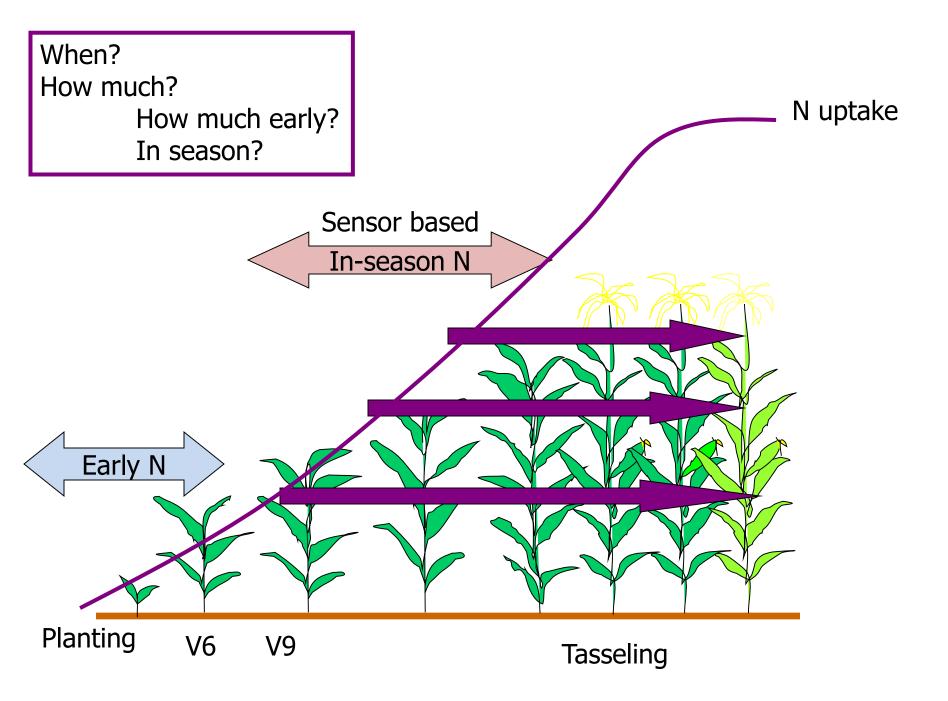
"It' cold - *like hell* - in Nebraska"

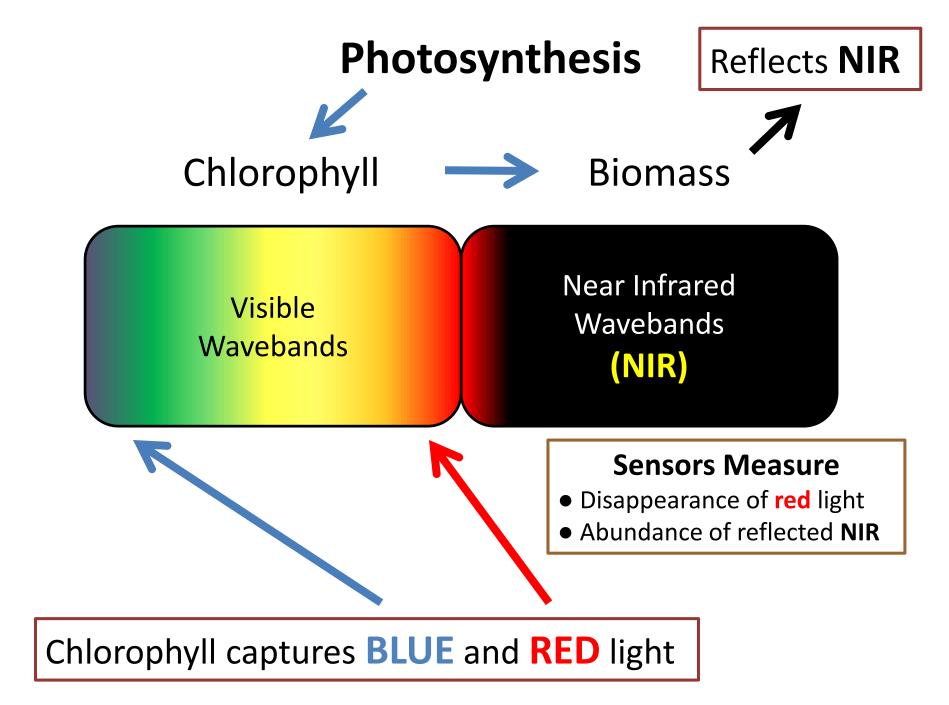
Jim Schepers 402-310-6150 james.schepers@gmail.com

Optimizing In-season Nitrogen Management

Dennis D. Francis and James S. Schepers







Normalize Vegetation Index Values to remove "field effects"



Compare all data to "Healthy Plants" that have the same:

Growth stage Cultivar (variety) Previous crop Water management Soil properties --- *except nutrients*

If one assumes all nutrients are adequate except for N, for example :

- Differences in crop vigor are probably related to plant N status -

Common Vegeta	tion Indices		
NDVI =	(NIR – Red) (NIR + Red)		
NDRE =	(NIR – Red Edge) (NIR + Red Edge)		
Chl Index =	(NIR – Red) (Red Edge – Red)	OR	(NIR)
Visible / NIR =	(Red) (NIR)		

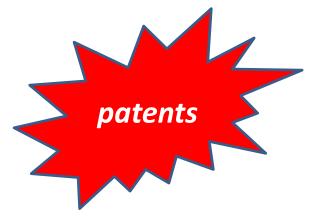


- Many factors can influence leaf chlorophyll content -

"Why not compare nitrogen recommendations using a common data set ?"

Algorithms have been developed using specific sensors that are associated with recommended agronomic practices

- Wave-band differences
- Reference Strategy (normalization)
- Opportunity for producer input
- Preplant N differences
- Yield (relative, predicted, not used)
- NUE input



Topcon



Holland Scientific



(Ag Leader)

NTech Industries



(Trimble)

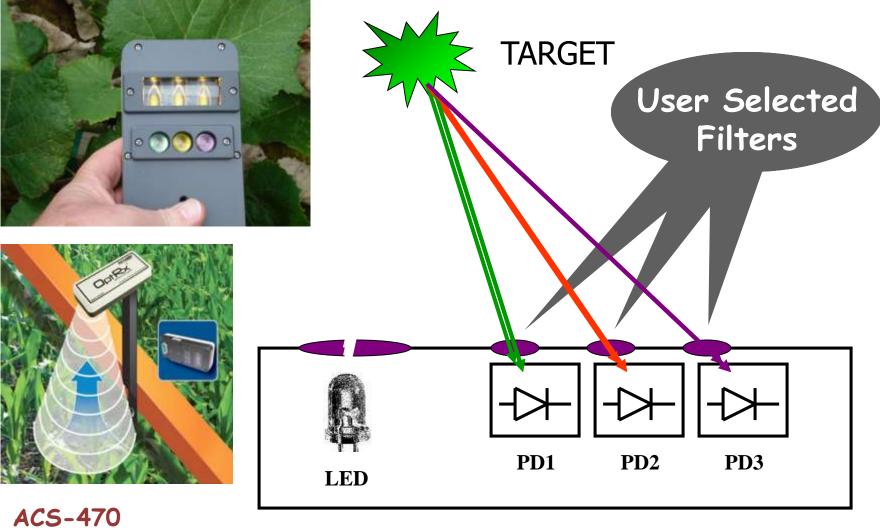


Crop Spec

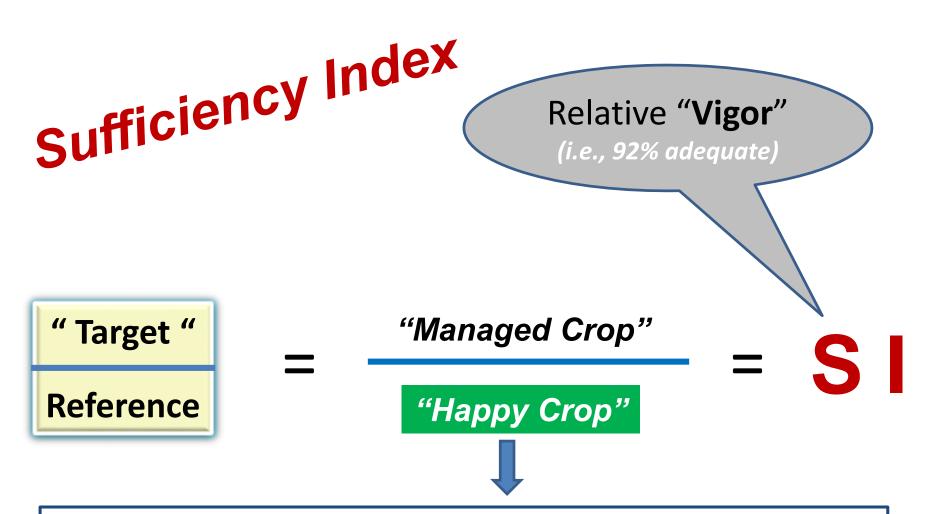
Foot-print changes with plant height



Modulation/Demodulation Using Polychromatic LEDs



SENSOR

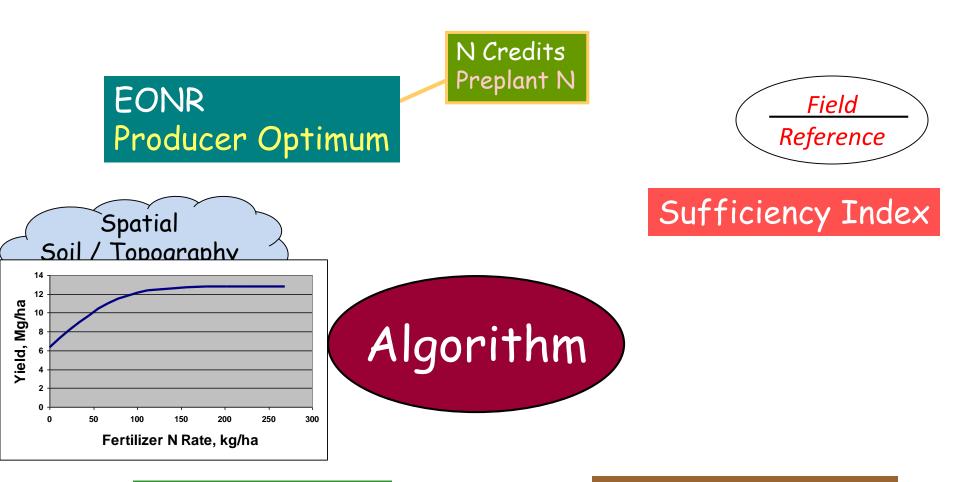


- N-rich (highest 3 consecutive seconds) GreenSeeker
- N-rich (average) Missouri
- Virtual reference from field with modest preplant N *Holland*

Reference Value Determination

German	Not used "Walk in the field"				
Missouri	"we filter off values <u>from an N-rich area</u> that would represent poor				
	or no stand and then take the <i>mean</i> of what remained". (Newell Kitchen)				
Oklahoma	"Reference values are tied to the readings we collect from the N-rich				
Okiunomu	strip (producers and research). " <i>(Bill Raun)</i> Earlier used highest 3-consecutive second value (30-point running average)				
	"Virtual reference" - 95-percentile value (2 Std. Dev. units above				
Holland	the mean) for histogram of vegetation index values from field strip receiving modest preplant N application. (~1/3 recommended rate)				
	"Drive-and-Apply" - Automatically updated virtual reference when starting				
	in average to above-average part of the field.				

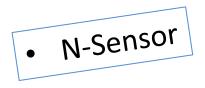




N Accumulation (based on growth stage)

Back-Off Strategy SI to start cutback SI to cut-off

German Algorithm



- Producer identifies poor part of the field and assigns the desired N rate.
- Similarly, the producer identifies a good part of the field and assigns the preferred N rate.
- Sensor readings are taken from each area.
- Linear regression algorithm is developed for variable rate application.

Developed for small grains with multiple applications.

Oklahoma Algorithm



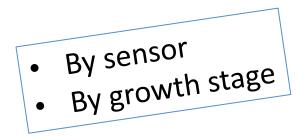
Assess crop growth and vigor via sensor readings:

- Record growing degree days (GDD) since planting
- Calculate potential yield based on NDVI / GDD data vs. yields from past years and locations
- Back calculate the difference in grain N content between reference and target plants
- Adjust for NUE

New Approach

- Use reference NDVI and yield data from multiple locations and years to generate sigmoid-shaped growth function
- Predict yield potential from NDVI using sigmoid function

Missouri Algorithm



Crop Sensor Stage Missouri N rate equation

Corn GreenSeeker V6-7 (12" to knee high)Corn GreenSeeker V8-10 (waist high)Corn GreenSeeker V11+ (chest high or taller)

Corn Crop Circle 210 V6-7 *Corn Crop Circle 210* V8-10 *Corn Crop Circle 210* V11+ (220 x ratio*) - 170 (170 x ratio) - 120 (160 x ratio) - 130

(330 x ratio) - 270 (250 x ratio) - 200 (240 x ratio) - 210

*Ratio = (Target visible/near-infrared) / (High-N visible/near-infrared)

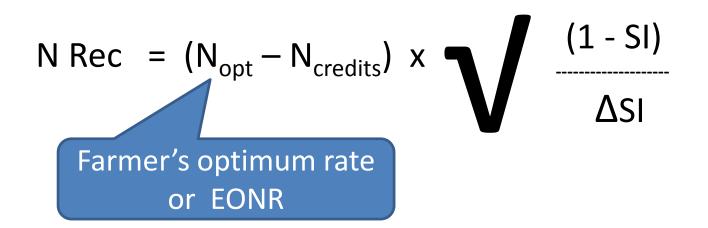
- Calibrated using field studies
- Minimum N-rate of 30 60 lb/acre regardless of sensor reading

Source: "Managing Nitrogen with Crop Sensors: WHY and HOW" (Scharf)

Holland / Schepers Algorithm

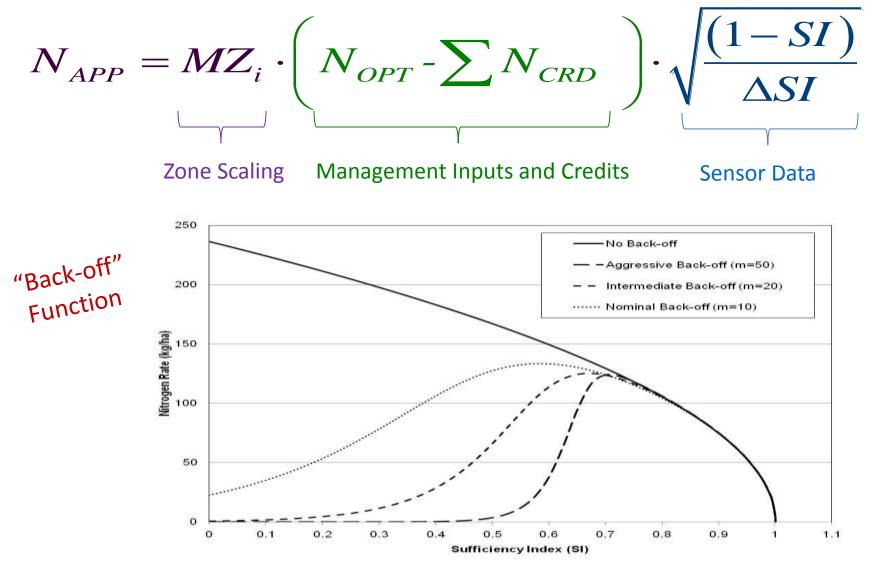


Based on the mathematical derivation from an **N-rate** vs. **yield** response function (quadratic component)



Source: "Derivation of a Variable Rate Nitrogen Application Model for In-Season Fertilization of Corn" (Holland and Schepers, Agron. J. 102:1415–1424 (2010)

*Holland-Schepers Generalized N-Rate Model:



*Reference

Holland, K. H., & Schepers, J. S. (2010). Derivation of a variable rate nitrogen application model for in-season fertilization of corn. *Agronomy Journal 102*:1415-1424.

Other Features

	Ν	Cut-Back	Yield	Management	Genetic
	Credits	Feature	Prediction	Zones	Potential
German	No	No	No	No	No
Missouri	No	No	No	No	No
Oklahoma	No	Yes / No	Yes	No	No
Holland	Yes	Yes	Νο	Yes	Yes

